

Jonathan Worthington French Perl Workshop 2007

$3.0 \times 10^8 \, \text{m/s}$

3.0 x 10⁸ m/s The fastest we can move information

3.0 x 10⁹ hz

3.0 x 10⁹ hz The number of cycles a 3GHz CPU does per second

The distance we can move data per cycle.*

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* If the CPU were a vacuum.

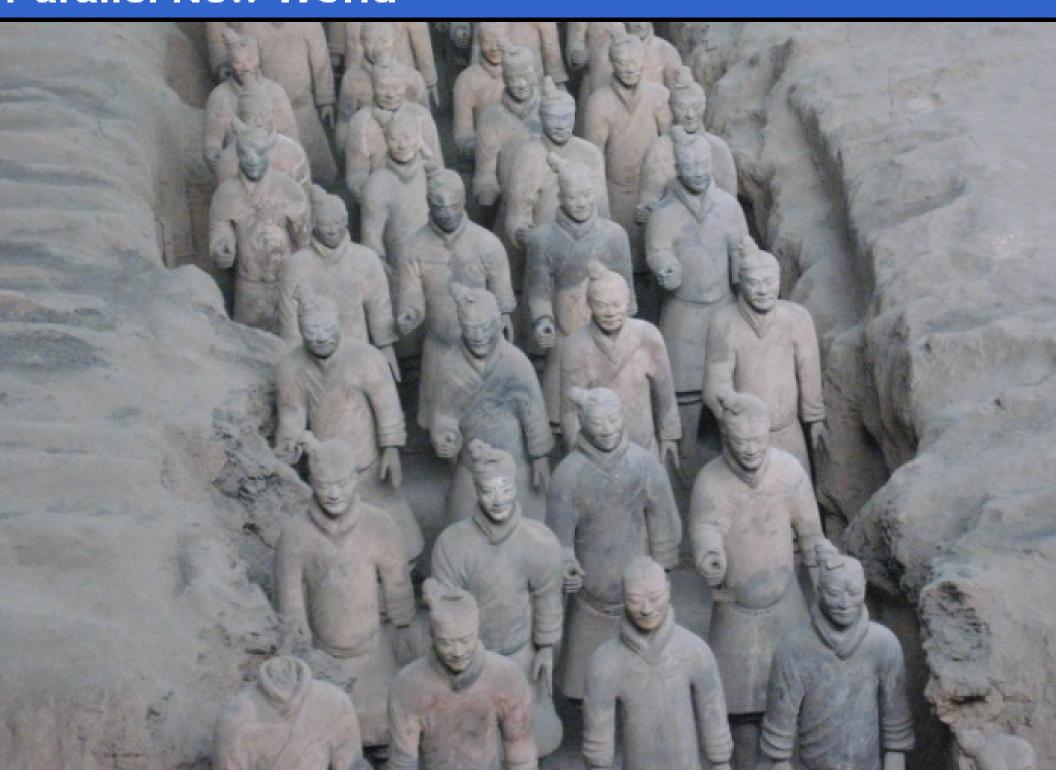
The distance we can move data per cycle.*

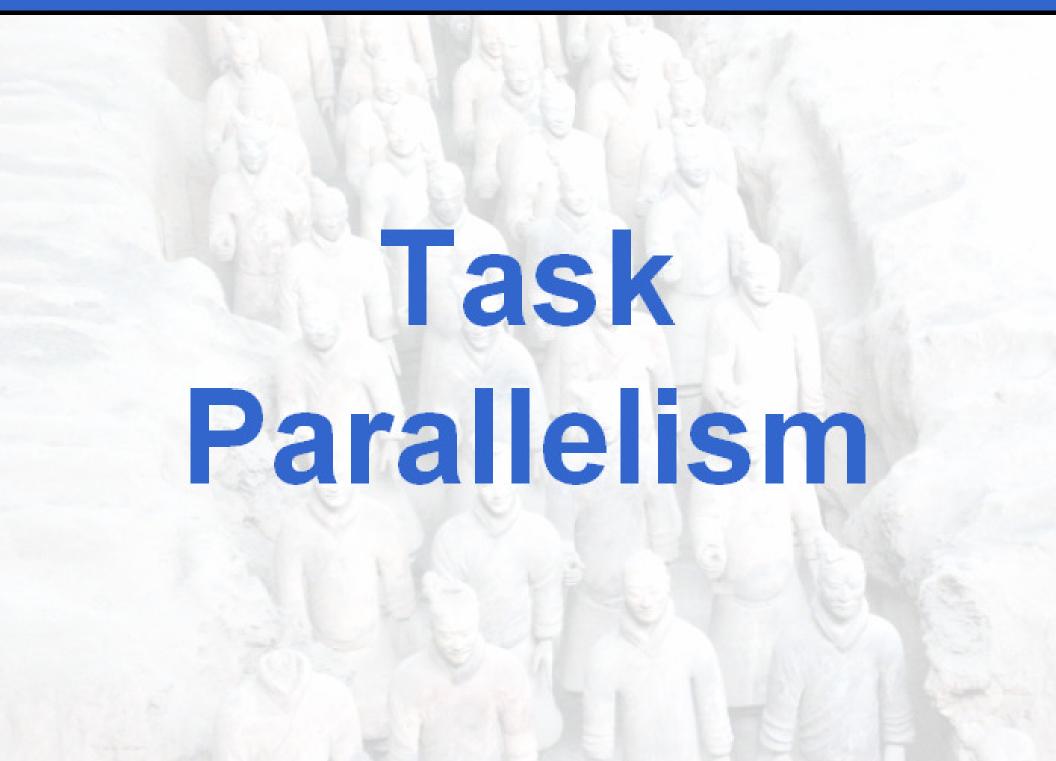
* If the CPU were a vacuum. (By the way, it's not. ☺)

Current leakage Capacitance effects Quantum effects

We can't just keep clocking up the cycles.

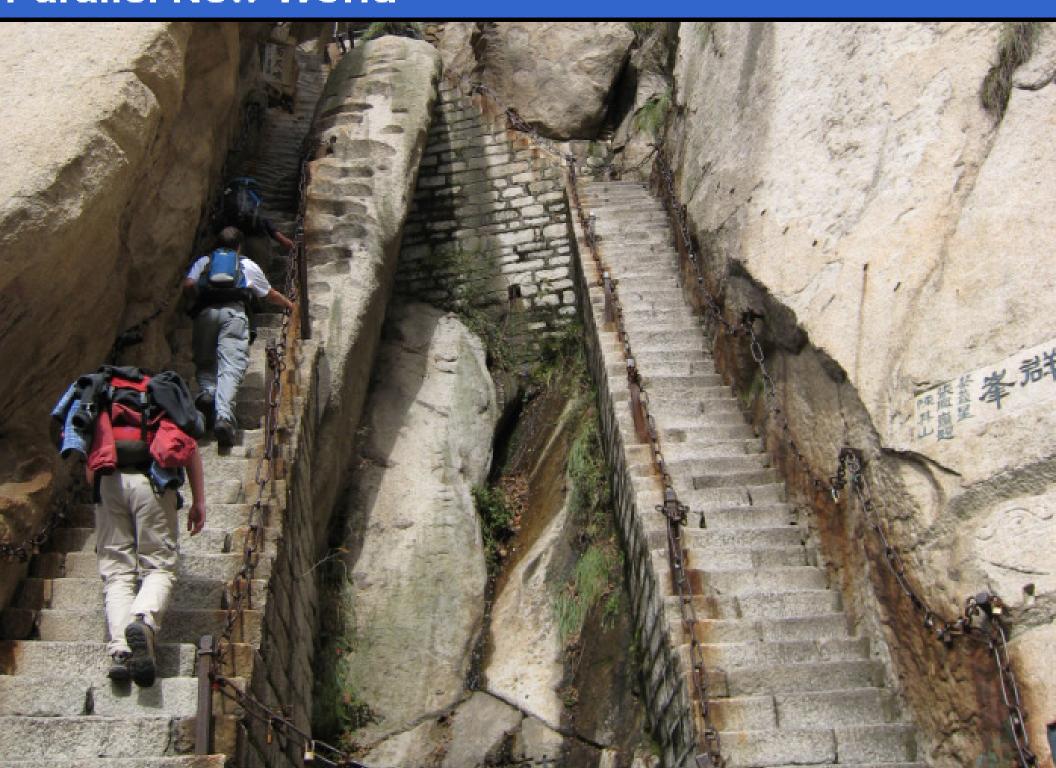
The Answer: Go parallel.

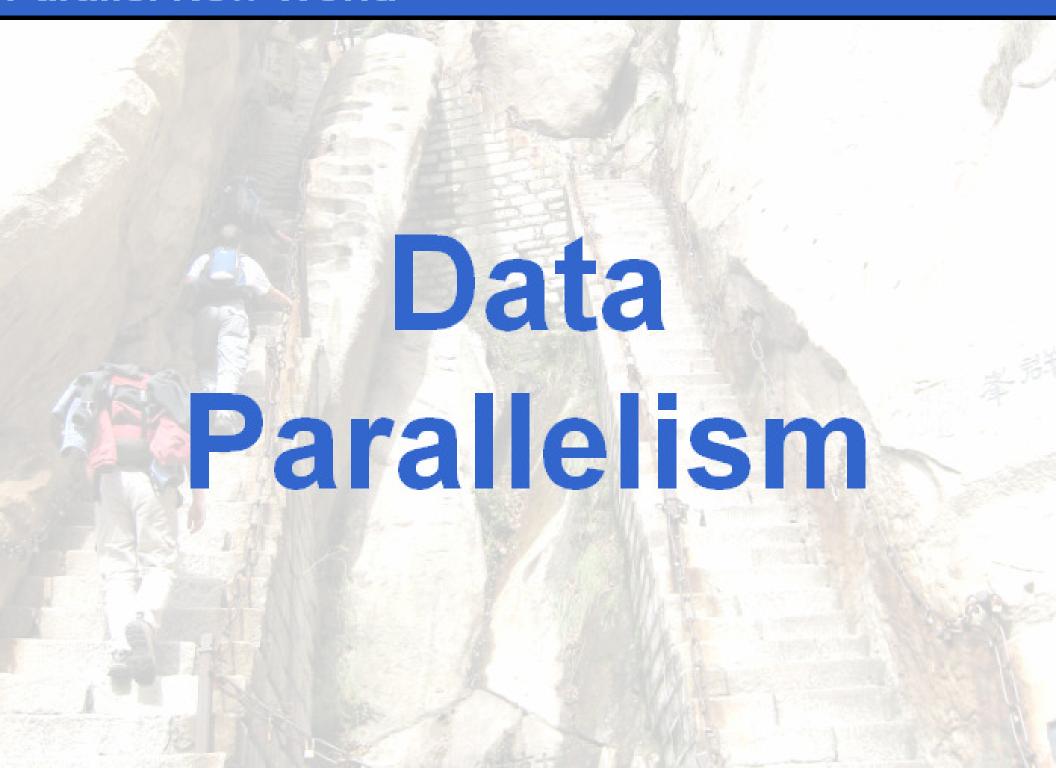




Task Parallelism

- Take a range of different tasks
- Run them in parallel
- Consider a game...
 - Rendering beautiful graphics
 - Doing Al for intelligent opponents
- Can do these two tasks in parallel
- Tasks will often need to communicate somehow





Data Parallelism

- Performing the same task on many items
- For example, calling the same method on every element of an array
- If we know it is safe, we can call the method over the array in parallel
 - Different execution units work on different elements of the array



Parallelism Primitives

Threads

- A thread has its own program counter and stack
- Lives in the same memory space as other threads in the process => communication by shared memory
- Usually, we create it and point it at a bit of code to start executing

<u>Mutexes</u>

- Short for <u>Mutual Ex</u>clusion
- Only one thread can hold the lock at a time
- If thread 1 has the mutex and thread 2 wants it, thread 2 must wait until thread 1 is finished with it
- Easy to implement directly on top of hardware primitives

<u>Semaphores</u>

- An integer value
- Initialize it to the number of resources available
- P operation acquires a resource:

```
sub P($s) { wait until $s > 0 then $s-- }
```

V releases it:

```
sub V($s) { $s++ }
```

Blame the Dutch for the naming. ☺





The Ten Thousand Threads Myth

 "If I start ten thousand threads my application will run about ten thousand times as fast!!!"

The Ten Thousand Threads Myth

- "If I start ten thousand threads my application will run about ten thousand times as fast!!!"
- Well, sure, if...
 - You've got 10,000 CPUs/cores...
 - And no scheduling overhead...
 - And virtually no inter-thread communication.

How many threads?

- If your application is CPU-bound there is no point having more threads than you have CPUs/cores.
- Having more...
 - Means the scheduler has more work so you get to run less code
 - Introduces more contention on locks with no gains

```
Thread 1
$acc_a.debit(100);
$acc_b.credit(100);
```

```
Thread 2

$total += $acc_a.bal

$total += $acc b.bal
```

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```

```
Thread 1

$acc_a.debit(100);
$acc_b.credit(100);
```

```
Thread 2
$total += $acc_a.bal
$total += $acc_b.bal
```

 If two threads are accessing the same bit of data, you need to control access to it

```
Thread 1

$acc_a.debit(100);
$acc_b.credit(100);
```

```
Thread 2

$total += $acc_a.bal
$total += $acc_b.bal
```

 Our program to get the balance across the accounts gets the wrong answer, because it sees an inconsistent state

<u>Deadlock</u>

 Deadlock occurs when you get circular waiting on a lock

```
Thread 1
lock $acc_a {
lock $acc_b {
...
}
```

```
Thread 2
lock $acc_b {
lock $acc_a {
...
}
```

<u>Deadlock</u>

 Deadlock occurs when you get circular waiting on a lock

```
Thread 1
lock $acc_a {
lock $acc_b {
...
}
```

```
Thread 2
lock $acc_b {
lock $acc_a {
...
}
```

```
Thread 1
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...
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Thread 2
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...
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...
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```

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 Deadlock occurs when you get circular waiting on a lock

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Thread 1
lock $acc_a {
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...
}
```

```
Thread 2
lock $acc_b {
lock $acc_a {
...
}
```

 Thread 1 requires lock A, Thread 2 requires lock B. Neither can proceed.

Lock Granularity Issues

- You have a hash table data structure
- You can have a lock over the whole data structure or a lock on every bucket in the hash (the place where the data is stored)
- Which to do depends on the kind of operations that will be performed most often on the hash

Lock Granularity Issues

- If you have a single lock for the entire hash...
 - Take one lock for any operation(s)
 - Only one access to the hash can proceed at a time
 - If you're mostly reading from the hash or updating existing values, you lose a lot of potential concurrency

Lock Granularity Issues

- If you have a lock for every element...
 - More concurrency on reads/updates
 - A write may need to resize the hash table => requires locking of every bucket (a LOT of locking overhead)!
 - Compound operations or iterating over the hash needs many locks
 - Can waste a lot of time juggling locks





Why CPUs have caches

- A CPU cache stores <u>copies</u> of sections of main memory
- Accessing main memory is slow (on the order of magnitude of 100s of CPU cycles)
 - You have to go off-chip
 - DRAM read speeds haven't kept up with CPU speed gains

What A Cache Looks Like

- Contains a number of Cache Lines, perhaps of length 128 bits (holds 4 32bit words), but it varies by CPU
- A cache line holds a copy of an area of main memory
- When the cache is full, have to choose a line to evict; random but not last used is a common policy

Reads And Writes With A Cache

- Reads are done through the cache; if the data isn't in the cache, fetched from main memory
- Write-through: when making a change, you bypass the cache and write directly to memory
- Write-back: you make changes to the line in the cache, and when that line is evicted the data is written to memory

Cache Line States For One CPU

- With a single CPU, a cache line can be in one of three states:
 - Invalid, when it's not holding a copy of any memory location
 - Valid, when it holds a copy of a memory location
 - Dirty, when the data it holds has been changed (update memory on eviction)

SMP Architecture

 The CPUs or cores are connected by a shared bus



- They can all see each others memory requests
- Note: SMP doesn't scale, as the more CPUs you get the more contention you get on the bus

Caches And Multiple CPUs

- Reading data through the cache is fine
 - Every CPU can have a copy of the data in its cache
 - Multiple threads reading shared memory is fine
- Note that all CPUs can see what other CPUs are reading

Caches And Multiple CPUs

- Writes are more complex...
 - We need other caches to toss their copies of the data, as it is about to become out of date
 - We start by doing an exclusive read
 - This gives us the data
 - All other CPUs see it and their caches evict those cache lines

Caches And Multiple CPUs

- The Modified state
 - When we modify data held in a cache line, its state changes to Modified
- If we see somebody else try to read a memory address and we have it cached and marked modified, we:
 - Jam their read
 - Write the modification to memory

Consequences for application design

- If multiple threads are reading from and writing to memory on the same cache line, the cache line is "pinging" between the CPUs
- Therefore...
 - Maximize thread local storage
 - Minimize writes to memory shared between threads

Consequences for locking

- A lock is just a bit of memory set to a value saying whether the lock is taken or not (or maybe saying who holds the lock, if anyone)
- Cache line for that memory location will ping between CPUs too
- Therefore, taking locks is expensive in terms of bus activity (and thus time)

False Sharing

- You have four threads numbered 1 to 4
- You have an array with four elements, all 32-bit words
- Thread 1 will read/write the first element, thread 2 will read/write the second element, etc.
- So we've got no sharing and we're nice and efficient, right?

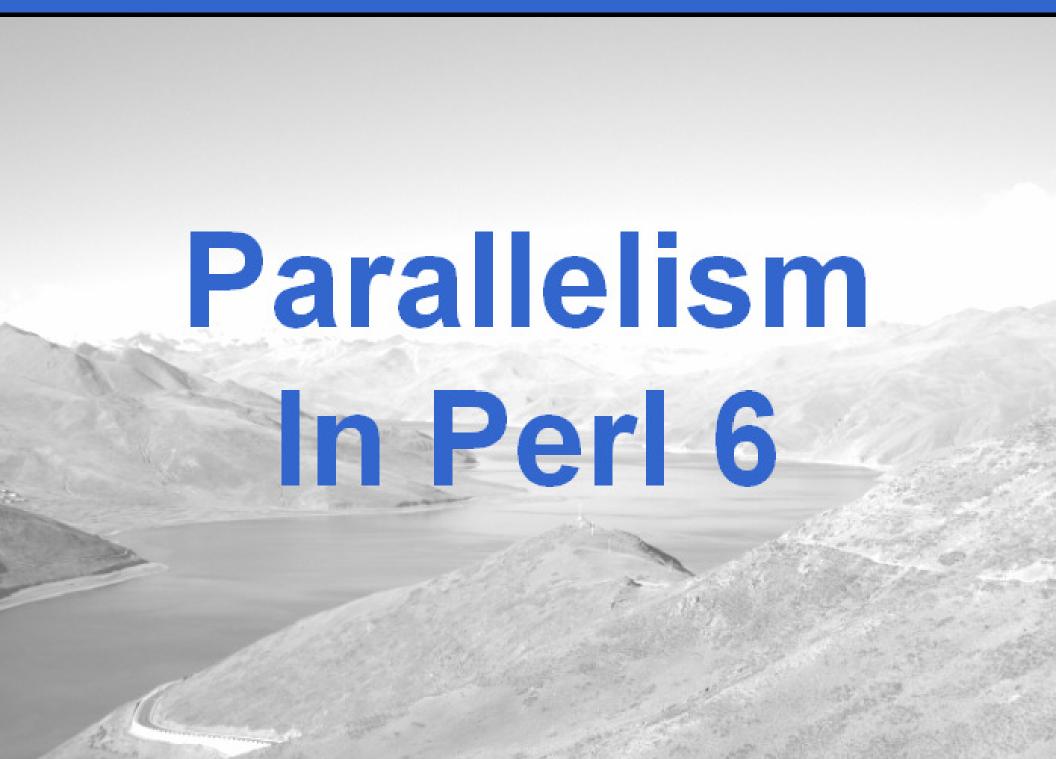
False Sharing

- •No. ⊗
- Cache lines hold many words
- Our array may lie all on a single cache line or at best be spread over two cache lines
- At the program level, there is no sharing of memory. At the hardware level, there is, due to cache line size.

Summary of cache issues

- If you want to write concurrent programs that perform well, you must think about its cache characteristics
- Use as much thread-local storage as possible
- Minimize lock taking (but larger locks limit concurrency – difficult trade-off)
- Beware of false sharing





The Big Picture

- Syntax and details are yet to be finalized, so anything I say may change
- Much more declarative than Perl 5
 - We say what we want and leave the computer to work out how to make it happen
- Support for both task based parallelism and data based parallelism

async blocks

 To say that a block of code should be executed asynchronously (e.g. in a thread of its own), prefix the block with async.

```
async {
    # Code in here runs in another thread
}
# Code here is still in original thread
```

async blocks

 It returns a thread object, which we can keep and use to control the thread if needed.

```
my $thread = async {
    # Code in here runs in another thread
# Numifies to the thread ID.
say "The thread has ID " ~ +$thread;
# Can do the usual thread operations...
$thread.join();
```

<u>Software Transactional Memory</u>

- A transaction is a sequence of operations that are guaranteed to:
 - Either complete in full or have no effect on the system at all
 - Take place atomically
- STM implements very lightweight and cache-sensitive transactions with these characteristics

<u>How STM Works, Roughly</u>

- We don't take any locks
- Whenever we make a change to some state (e.g. assign to a variable), we don't change the original, but instead note the change that took place
- Reads inside our transaction see the changes
- Reads outside of it don't see them

<u>How STM Works, Roughly</u>

- If we have run all of the instructions successfully, we try to commit the transaction
 - Check none of the values that we read or modified have changed
 - If none did, apply our changes
 - Otherwise, run our transaction from the start again, with updated values

<u>How STM Works, Roughly</u>

- If an error occurs inside of our transaction...
 - We didn't actually change anything, just noted our changes
 - So just discard the transaction information, and it's as if we never ran it

STM in Perl 6

 Write an atomic block to state that the code inside it is to run as a transaction.

```
atomic {
    $acc_a.debit(100);
    $acc_b.credit(100);
}
```

 Note that you can not do any I/O inside a transaction, as we can't roll that back; trying to do so is a fatal error.

<u>Advantages Of STM</u>

- Declarative: frees the programmer from worrying about locking issues
- A good implementation of STM will result in little locking taking place under the hood, making the application much more scalable
- Your program always makes progress: if a transaction fails at commit time, it's because another one succeeded

Data Parallelism

- Possible when we are performing the same operation over all elements of an aggregate, for example an array
- Perl 6 provides ways to perform a range of operations over all elements of an array:

```
# Element-wise addition of two arrays
my @c = @a >>+<< @b;
# Call a method on every element
@dogs>>.wag_tail();
```

Parallel New World

Data Parallelism

- When you use the hyper, cross or reduction operators, it's not just cool syntax
- You are declaring that there are no data dependencies between operations on elements of the array
- From this, the compiler can infer that it is safe to parallelize the operations

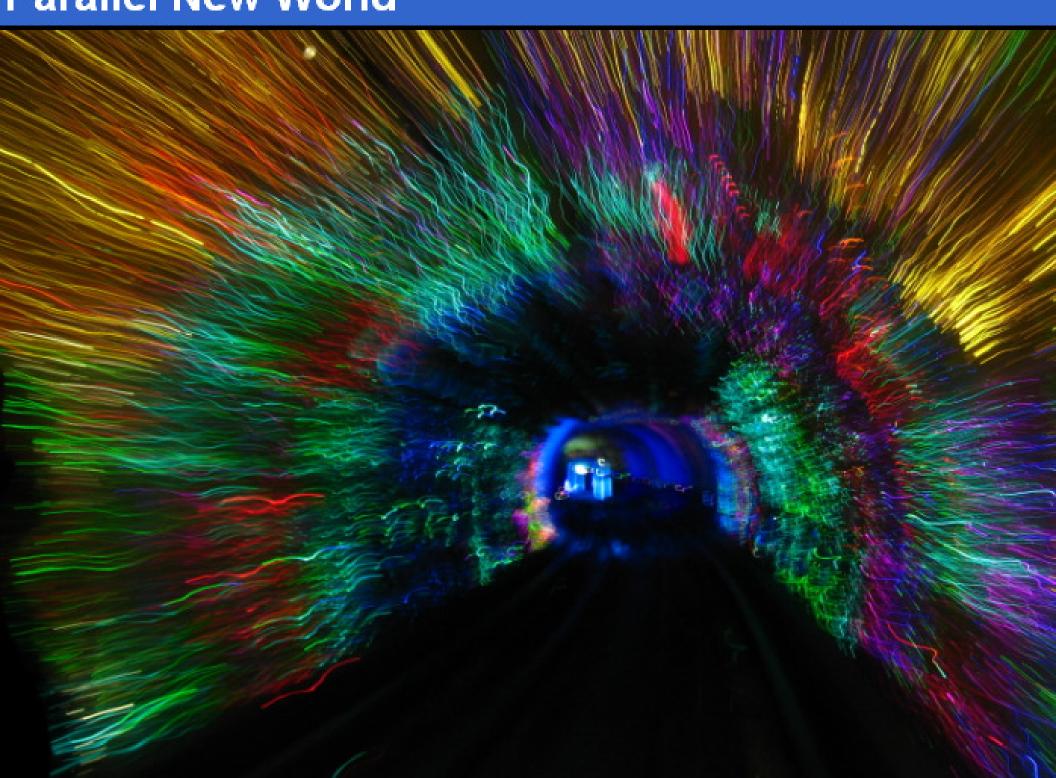
Data Parallelism

 You will probably use a pragma to indicate that you want such operations to be parallelized.

```
use Parallel::Hypers; # I made this up :-)
```

- These pragmas will almost certainly be written as modules – probably in Perl
- Powerfully allows us to separate concerns – how to parallelize an operation from the operation itself

Parallel New World





Concurrency Annotations

 Another idea being worked on is annotating variables with what kind of concurrency control they require

 Then the compiler is responsible for enforcing these locking regimes on accesses to the variables

Lock Free Data Structures

- We have seen that taking locks limits performance and scalability
- What if we could build data structures that...
 - Allowed concurrent operation
 - Don't require taking of locks
 - Will still guarantee that we don't end up with an inconsistent state

Atomic Compare And Swap

 Many CPUs provide a CAS (Atomic Compare And Swap) operation

```
seen = CAS(addr, expected, replacement)
```

- addr is a memory address
- expected is what it should contain
- replacement is what we store there
 if it contains the expected value
- seen is the value that was there

<u>Using CAS</u>

- CAS is the primitive concurrency operation upon which we can build all others (the theorists proved it)
- For example, a bad implementation of a mutex using CAS is:

```
sub take {
    while (CAS($mutex, 0, 1) != 0) { }
}
sub release {
    CAS($mutex, 1, 0) || die "WTF?!";
}
```

Making Any Data Structure Lock Free

- If you add a level of indirection, you end up with a memory location containing a pointer (reference) to the data structure
- You make a copy of the data structure at that pointer
- You modify the copy
- You then try and use CAS to swap the original pointer with that of your copy

Making Any Data Structure Lock Free

- This has the (good) property that if your change fails to be made, it's because another thread made one => program made progress ☺
- For certain data structures, you can do MUCH more efficient things built on top of CAS.
- It's really hard to get right => need smart people to write libraries of these

The End

Questions?

Merci!